Konik Kothari +1 (217)-417-6832 🛛 kkothar3@illinois.edu **?** github.com/kkothari93

Education

University of Illinois at Urbana-Champaign

Ph.D. candidate in Electrical and Computer Engineering, GPA: 3.92/4.0 **Thesis research**: Machine learning for inverse problems in imaging **Advisor**: Prof. Ivan Dokmanić

Relevant Coursework: High-dimensional statistics, Computer Vision, Random Processes, Neural Networks and deep learning, Reinforcement Learning and MDPs, Pattern Recognition, Advanced Data Analysis, Applied Parallel Programming

M.S., Mechanical Engineering

Indian Institute of Technology, Delhi, New Delhi, India B.Tech in Mechanical Science and Engineering, GPA: 9.13/10.0

Publications [Scholar]

- Random mesh projectors for inverse problems ICLR 2019 *Authors: K. Kothari, S. Gupta, M. de Hoop, I. Dokmanić* We developed a method to regularize very ill-posed inverse problems via random projections that generalizes robustly out-of-dataset. We collaborated with NASA Insight mission to successfully estimate subsurface velocity profiles of Mars from "Marsquakes"; received best poster award in UIUC ECE graduate poster session.
- Learning the geometry of wave-based imaging (under review) arXiv:2006.05854v2 Authors: K. Kothari, M. de Hoop, I. Dokmanić Based on microlocal analysis and Fourier integral operators (FIOs), we proposed a novel neural architecture for wave-based imaging that generalizes out-of-distribution, is interpretable and needs fewer samples to train.
- Globally injective ReLU networks (under review) arXiv:2006.08464 Authors: M. Puthawaala, K. Kothari, Dokmanić, M. Lassas, M. de Hoop We presented necessary and sufficient conditions for when ReLU networks are globally injective. Our experiments demonstrated better inference performance. This is crucial for solving inverse problems under GAN priors.
- Magellan: A Personalized Travel Recommendation System Using Transaction Data, CIKM 2020 Authors: K. Kothari, D. Gelda, Wei Zhange, Hao Yang We developed an end-to-end real-time travel recommendation system using only card transaction data.
- Parsimonious Seismic Tomography with Poisson Voronoi Projections: Methodology and Validation, Seismological Research Letters (2020) 91 (1), 343-355 Authors: H Fang, RD van der Hilst, MV de Hoop, **K Kothari**, S Gupta, I Dokmanić We applied random mesh projections to real seismic data and achieved SoTA uncertainty quantification results.
- Mechanical response of two-dimensional polymer networks: role of topology, rate dependence and damage accumulation, J. Appl. Mech 85(3), 031008, Jan 2018
 Authors: K. Kothari, Y. Hu, S. Gupta, A. Elbanna
 We developed a defomation model for crosslinked polymer networks explaining how sacrifical bonds toughen hydrogels.
- Localization and instability in sheared granular materials: Role of friction and vibration, Phys. Rev. E 95, 022901, Feb 2017 Authors: K. Kothari, A. Elbanna We developed a stress-strain model for granular materials under shear load explaining slip-stick phenomena.

Technical Skills

- Python, C/C++, MPI, CUDA, Pig, Hive, ${\rm I\!AT}_{\rm E\!X}$
- Tensorflow, PyTorch

Jan 2018 – Present

Aug 2015 - May 2017

July 2010 - May 2014

Work experience

• Visa Research: Research Intern, Data Analytics Team Worked on building an a travel recommendation system mining billions of transactions	Summer 2018
• NVIDIA : Data Science Intern, Intelligent Video Analytics Team Worked on anomaly detection in vehicle trajectory data	Summer 2019
• GlaxoSmithKline Consumer Healthcare, India Technical Supply Chain Engineer Future Leader's Program: Worked in a rotation engineering program in all verticals of supp	May, 2014-May, 2015 oly chain.
Projects	
Face-editing using GANs	Spring 2018
• Built an interactive face-editing application using various variants of GANs (WGAN/ WG.	AN-GP/ SWGAN)
One-shot learning using memory-augmented neural networks	Fall 2016
Augmented a neural network with an external memory that has a recurrent neural network control to read and write relevant representation of data in the external memory.Achieved accuracy greater than 80% within just 3 presentations of a class for the Omniglot	ontroller which is trained t dataset
Action-recognition using Deep Neural Networks	Fall 2016
• Implemented a recurrent-neural network that classified video action data in the UCF-101 extracted by fine-tuning a pre-trained VGGNet.	data-set. Features were
CUDA Accelerated Molecular Dynamics (MD)	Fall 2015
• Developed million-particle CUDA accelerated MD and Markov Chain Monte Carlo simulation tions like memory coalescing, warp unrolling and shared memory optimization.	ons using GPU optimiza-
Reinforcement learning in OpenAI gym	Fall 2017
\bullet Developed the actor-critic algorithm for continuous control in MountainCarContinuous-v0 $$	using neural networks
Google Foobar Coding Challenge	Jan 2018
• Completed all 5 levels of the Google Foobar challenge (a secret invite-only challenge)	
Teaching Experience	
Digital Imaging (ECE558) , <i>UIUC</i> Held office hours for a class of 35 graduate students discuss various imaging modalities.	Spring 2018
Engineering Materials (ME330) , <i>UIUC</i> Conducted labs for 16 undergraduate students on tension/compression tests, impact tests, composition	Spring 2016, Fall 2016 osites, alloy casting etc.
Introduction to statics (TAM210/211), UIUC Held discussion sections with freshmen/ sophomores to solve mechanics problems.	Fall 2017
Mechanical Engineering Drawing (MEP201), <i>IIT Delhi</i> Helped a class of > 60 undergraduate students with weekly engineering design in-class assignment	Spring 2014 ats.
Mentorship experience	
Mechanical Design Coordinator, Robotics Club, IIT Delhi	2013-2014

• Mentored a group of 14 sophomore students to build autonomous robots and manage club operations

• Held workshops on campus for freshmen to give them hands-on experience of building robots